

ECE No. 13.11/13H.00: Braking (ABS: Anti-lock Brake System) Technical requirement

The 61th Asia Expert meeting
5th - 6th Feb. 2020



JAPAN AUTOMOBILE STANDARDS INTERNATIONALIZATION CENTER

ECE No. 13.11/13H.00: Braking (ABS)



<Contents>

1. The main purpose of this regulation
2. Scope
3. Basic system structure of ABS
4. Summary of performance requirements
5. Detail of performance requirements
6. General requirements

Note:

Basically, the explanation is based on 13H.00

1. The main purpose of this regulation

Definition (13 Annex13/13H Annex6):

2.1

An “anti-lock system” is a part of a service braking system which automatically controls the degree of slip, in the direction of rotation of the wheel(s), on one or more wheels of the vehicle during braking.



2. Scope

ECE No. 13.11: M2, M3, N*

(Mandatory: M2, M3, N2 and N3 with not more than 4 axles)

ECE No. 13H.00: M1, N1*

(if fitted)

*N1 can use ECE No. 13 or 13H based on country's decision.

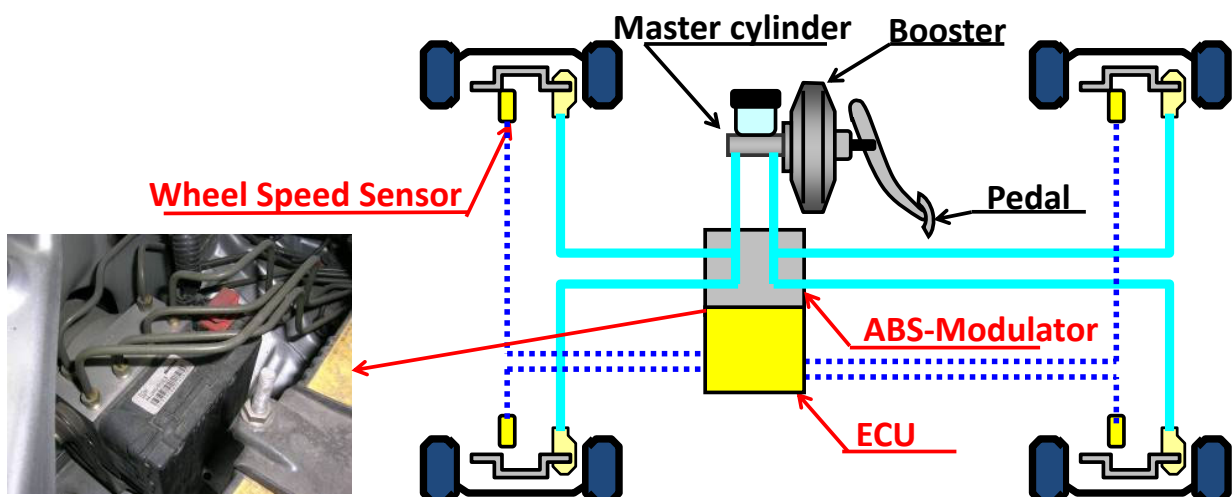
3. Basic system structure of ABS

Following devices are added to the brake system without ABS.

Wheel Speed Sensor: Detect the wheel is rotating or not

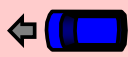
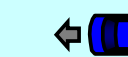
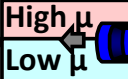
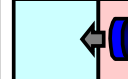
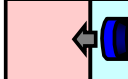
ABS-Modulator: Control the braking force for each wheels

ECU: Control ABS-Modulator based on related parameters



4. Summary of performance requirements (1/2)

The table of requirements

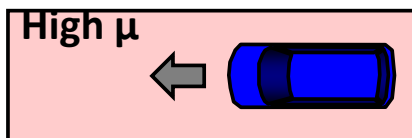
Road surface	High μ	Low μ	High μ / Low μ	Low μ / High μ	High μ / Low μ
Requirement					
Vehicle speed (km/h)	40, 120	40, 120	50	40, 120	50
$\varepsilon = \frac{Z_{AL}}{k_M} \geq 0.75$	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>		
No wheel lock $V \geq 15$ km/h	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Yaw angle < 15 deg.	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Not deviate 3.5m lane	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Steering angle 120° / 240°			<input type="radio"/>		
Not cross Lane boundary			<input type="radio"/>		
Rise Deceleration					<input type="radio"/>

5

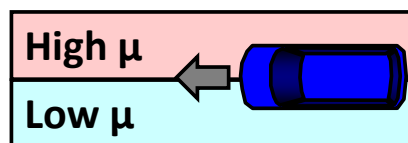
4. Summary of performance requirements (2/2)

Various road conditions

A : High μ road surface
About 0.8

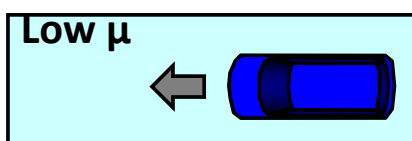


C : μ split (different μ on left / right)

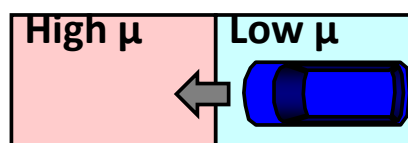


$$\begin{aligned} \text{High } \mu &\geq 0.5 \\ \frac{\text{High } \mu}{\text{Low } \mu} &\geq 2 \end{aligned}$$

B : Low μ road surface
0.3 or less

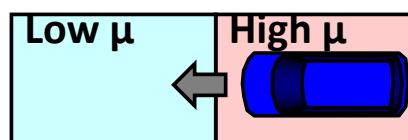


D : μ jump (Low μ to High μ)



$$\begin{aligned} \text{High } \mu &\geq 0.5 \\ \frac{\text{High } \mu}{\text{Low } \mu} &\geq 2 \end{aligned}$$

E : μ jump (High μ to Low μ)



6

5. Detail of performance requirements (1/5)

Efficiency of ABS (13H Annex6 5.2.1)

The efficiency of brake performance without ABS and with ABS is defined as below.

To prevent the slip, the weaken the braking force.
If to do so, the braking distance becomes be more longer...
But, the situation is not good. Then, the criteria is defined.

$$\varepsilon = \frac{Z_{AL}}{K_M} \geq 0.75$$

Z_{AL} : The brake performance with ABS

K_M : The brake performance without ABS

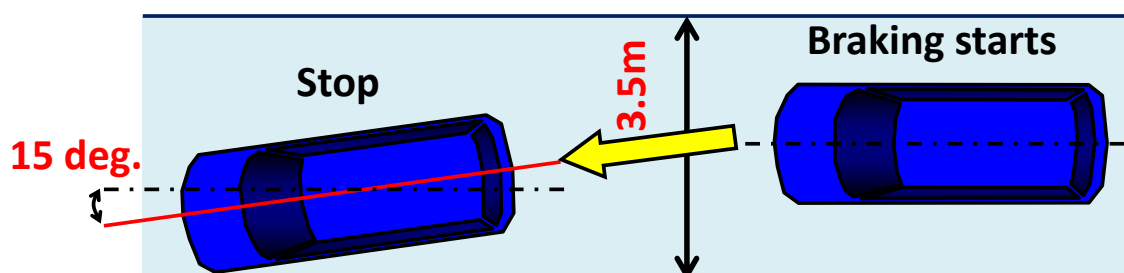
7

5. Detail of performance requirements (2/5)

Wheel lock, Yaw angle, Deviation (13H Annex6 5.3.6)

- ✓ The wheel lock is permitted when the vehicle speed is less than 15 km/h. (wheel lock is not occurred at exceed 15kn/h)
- ✓ The vehicle shall not exceed a yaw angle of 15 deg.
- ✓ The vehicle shall not deviate from a 3.5 m wide lane.

This requirement is applied for all ABS tests.



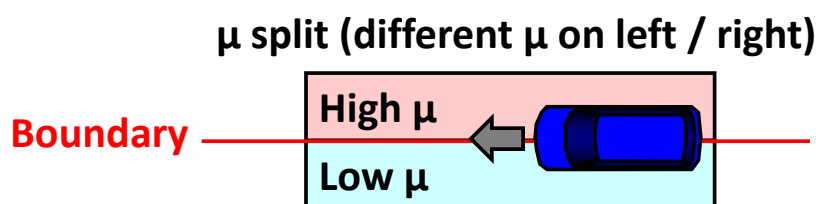
8

5. Detail of performance requirements (3/5)

Steering angle, not cross lane boundary (13H Annex6 5.3.7)

- ✓ Steering correction is permitted, if the angular rotation of the steering control is within 120 deg. during the initial 2 seconds, and not more than 240 deg.
- ✓ No part of the outer tyres shall cross this boundary.

This requirement is applied only for μ split road test.

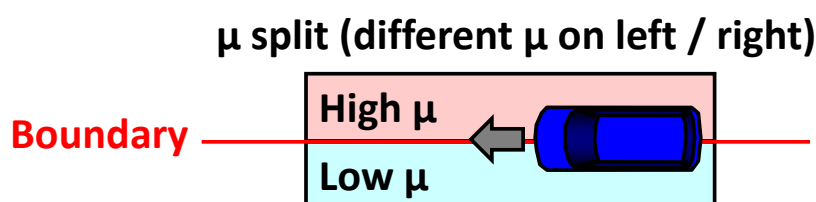


5. Detail of performance requirements (4/5)

Steering angle, not cross lane boundary (13H Annex6 5.3.7)

- ✓ Steering correction is permitted, if the angular rotation of the steering control is within 120 deg. during the initial 2 seconds, and not more than 240 deg.
- ✓ No part of the outer tyres shall cross this boundary.

This requirement is applied only for μ split road test.

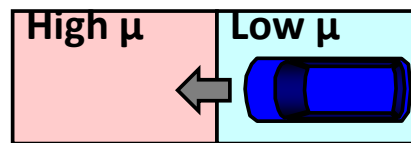


5. Detail of performance requirements (5/5)

Rise Deceleration (13H Annex6 5.3.3)

- ✓ The deceleration of the vehicle shall rise to the appropriate high value within a reasonable time.

This requirement is applied only for μ jump (Low μ to High μ) road test.

 μ jump (Low μ to High μ)

The braking force can be increase, because the friction between tyre and road can be increase on High μ road .

So, The deceleration shall be risen.

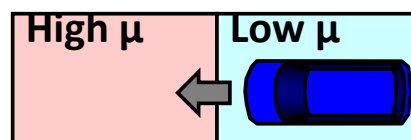
The deceleration (braking force) is low, because to prevent slip on Low μ road.

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The braking force can be increase, because the friction between tyre and road can be increase on High μ road .

So, The deceleration shall be risen.

The deceleration (braking force) is low, because to prevent slip on Low μ road.

6. General requirements (1/3)

13H Annex6 4.1

Any electrical failure or sensor anomaly that affects the system with respect to the functional and performance requirements shall be signalled to the driver by a specific optical warning signal. The yellow warning signal specified in paragraph 5.2.21.1.2. of this Regulation shall be used for this purpose.



(UN-R121)

13

6. General requirements (2/3)

13H Annex6 4.2

In the event of a single electrical functional failure which only affects the anti-lock function, as indicated by the above-mentioned yellow warning signal, the subsequent service braking performance shall not be less than 80 per cent of the prescribed performance according to the Type-0 test with the engine disconnected.

ABS failure criteria	
Initial braking speed	100km/h
Stopping distance	$0.1V + 0.075v^2$ (85m)
Mean deceleration	5.15 m/s ² (80% of Type-0)
Pedal Force	65 to 500N

14

6. General requirements (3/3)

13H Annex6 4.3

The operation of the anti-lock system shall not be adversely affected by magnetic or electrical fields. (This shall be demonstrated by compliance with Regulation No. 10, 02 series of amendments).

13H Annex6 4.3

A manual device may not be provided to disconnect or change the control mode of the anti-lock system.

Thank you!